

# Introduction



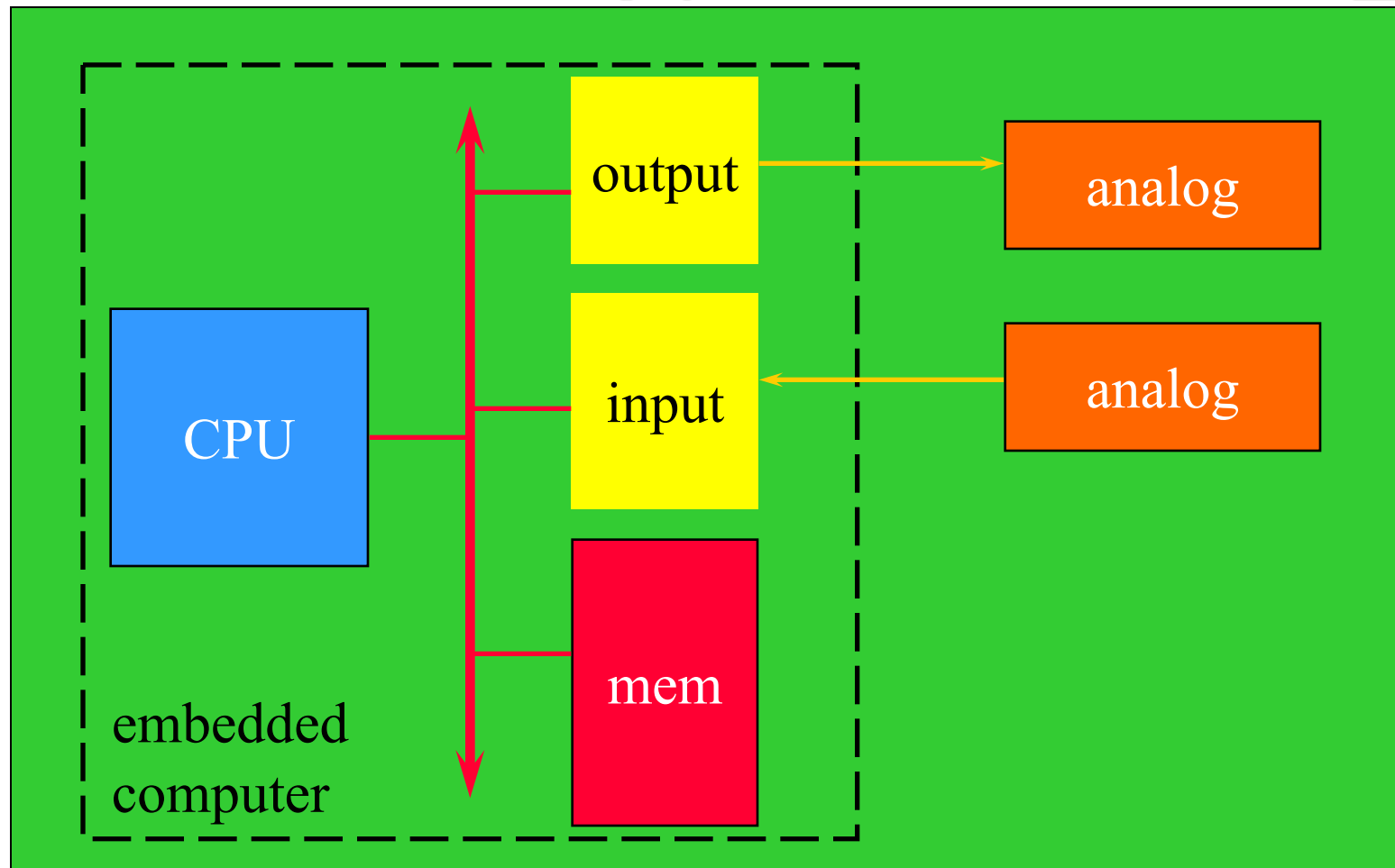
- What are embedded systems?
- Challenges in embedded computing system design.
- Design methodologies.

# Definition



- **Embedded system**: any device that includes a programmable computer but is not itself a general-purpose computer.
- Take advantage of application characteristics to optimize the design:
  - don't need all the general-purpose bells and whistles.

# Embedding a computer



# Examples



- Personal digital assistant (PDA).
- Printer.
- Cell phone.
- Automobile: engine, brakes, dash, etc.
- Television.
- Household appliances.
- PC keyboard (scans keys).

# Early history



- Late 1940's: MIT Whirlwind computer was designed for real-time operations.
  - Originally designed to control an aircraft simulator.
- First microprocessor was Intel 4004 in early 1970's.
- HP-35 calculator used several chips to implement a microprocessor in 1972.

# Early history, cont'd.



- Automobiles used microprocessor-based engine controllers starting in 1970's.
  - Control fuel/air mixture, engine timing, etc.
  - Multiple modes of operation: warm-up, cruise, hill climbing, etc.
  - Provides lower emissions, better fuel efficiency.

# Microprocessor varieties



- **Microcontroller:** includes I/O devices, on-board memory.
- **Digital signal processor (DSP):** microprocessor optimized for digital signal processing.
- Typical embedded word sizes: 8-bit, 16-bit, 32-bit.

# Application examples



- Simple control: front panel of microwave oven, etc.
- Canon EOS 3 has three microprocessors.
  - 32-bit RISC CPU runs autofocus and eye control systems.
- Analog TV: channel selection, etc.
- Digital TV: programmable CPUs + hardwired logic.



# Automotive embedded systems



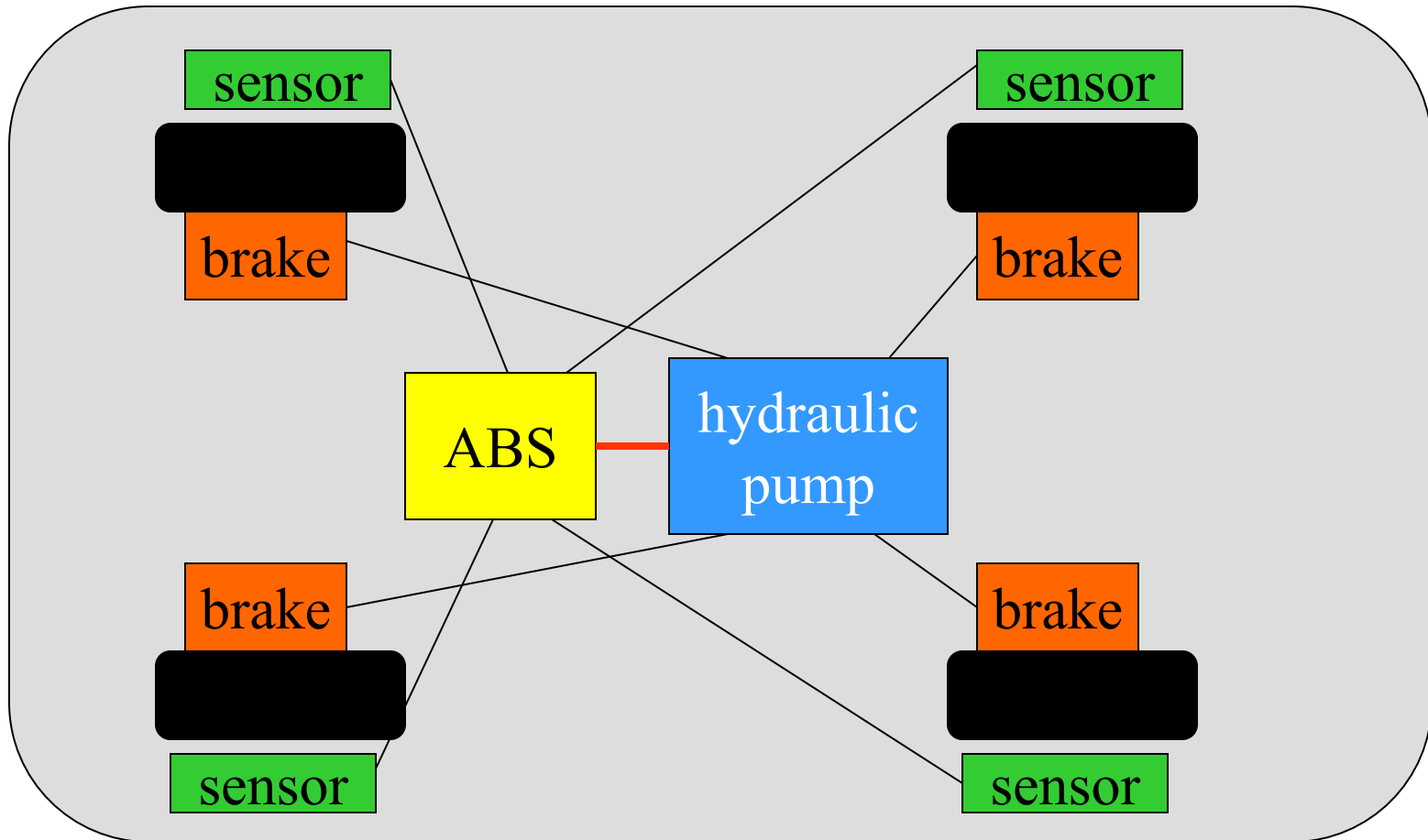
- Today's high-end automobile may have 100 microprocessors:
  - 4-bit microcontroller checks seat belt;
  - microcontrollers run dashboard devices;
  - 16/32-bit microprocessor controls engine.

# BMW 850i brake and stability control system



- **Anti-lock brake system (ABS):** pumps brakes to reduce skidding.
- **Automatic stability control (ASC+T):** controls engine to improve stability.
- **ABS and ASC+T communicate.**
  - ABS was introduced first---needed to interface to existing ABS module.

# BMW 850i, cont'd.



# Characteristics of embedded systems



- Sophisticated functionality.
- Real-time operation.
- Low manufacturing cost.
- Low power.
- Designed to tight deadlines by small teams.

# Functional complexity



- Often have to run sophisticated algorithms or multiple algorithms.
  - Cell phone, laser printer.
- Often provide sophisticated user interfaces.

# Real-time operation



- Must finish operations by deadlines.
  - **Hard real time:** missing deadline causes failure.
  - **Soft real time:** missing deadline results in degraded performance.
- Many systems are **multi-rate**: must handle operations at widely varying rates.

# Non-functional requirements



- Many embedded systems are mass-market items that must have low manufacturing costs.
  - Limited memory, microprocessor power, etc.
- Power consumption is critical in battery-powered devices.
  - Excessive power consumption increases system cost even in wall-powered devices.

# Design teams



- Often designed by a small team of designers.
- Often must meet tight deadlines.
  - 6 month market window is common.
  - Can't miss back-to-school window for calculator.



# Why use microprocessors?



- Alternatives: field-programmable gate arrays (FPGAs), custom logic, etc.
- Microprocessors are often very efficient: can use same logic to perform many different functions.
- Microprocessors simplify the design of families of products.

# The performance paradox



- Microprocessors use much more logic to implement a function than does custom logic.
- But microprocessors are often at least as fast:
  - heavily pipelined;
  - large design teams;
  - aggressive VLSI technology.

# Power



- Custom logic is a clear winner for low power devices.
- Modern microprocessors offer features to help control power consumption.
- Software design techniques can help reduce power consumption.

# Challenges in embedded system design



- How much hardware do we need?
  - How big is the CPU? Memory?
- How do we meet our deadlines?
  - Faster hardware or cleverer software?
- How do we minimize power?
  - Turn off unnecessary logic? Reduce memory accesses?

# Challenges, etc.



- Does it really work?
  - Is the specification correct?
  - Does the implementation meet the spec?
  - How do we test for real-time characteristics?
  - How do we test on real data?
- How do we work on the system?
  - Observability, controllability?
  - What is our development platform?

# Design methodologies



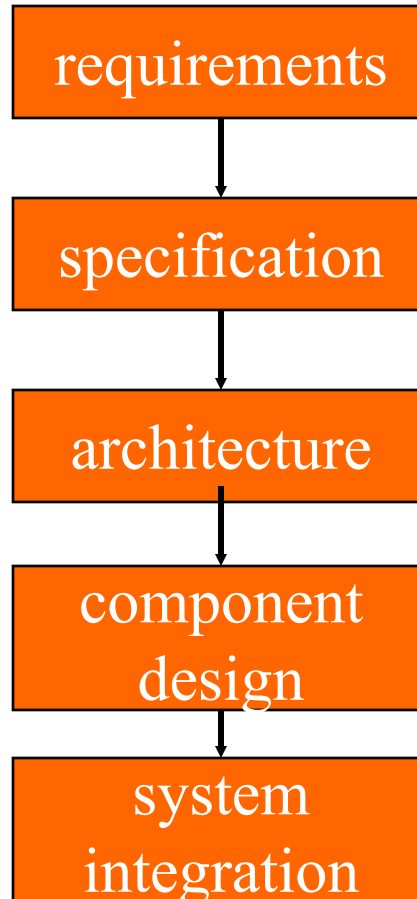
- A procedure for designing a system.
- Understanding your methodology helps you ensure you didn't skip anything.
- Compilers, software engineering tools, computer-aided design (CAD) tools, etc., can be used to:
  - help automate methodology steps;
  - keep track of the methodology itself.

# Design goals



- Performance.
  - Overall speed, deadlines.
- Functionality and user interface.
- Manufacturing cost.
- Power consumption.
- Other requirements (physical size, etc.)

# Levels of abstraction





# Top-down vs. bottom-up



- Top-down design:
  - start from most abstract description;
  - work to most detailed.
- Bottom-up design:
  - work from small components to big system.
- Real design uses both techniques.

# Stepwise refinement



- At each level of abstraction, we must:
  - **analyze** the design to determine characteristics of the current state of the design;
  - **refine** the design to add detail.

# Requirements



- Plain language description of what the user wants and expects to get.
- May be developed in several ways:
  - talking directly to customers;
  - talking to marketing representatives;
  - providing prototypes to users for comment.

# Functional vs. non-functional requirements



- Functional requirements:
  - output as a function of input.
- Non-functional requirements:
  - time required to compute output;
  - size, weight, etc.;
  - power consumption;
  - reliability;
  - etc.

# Our requirements form



name

purpose

inputs

outputs

functions

performance

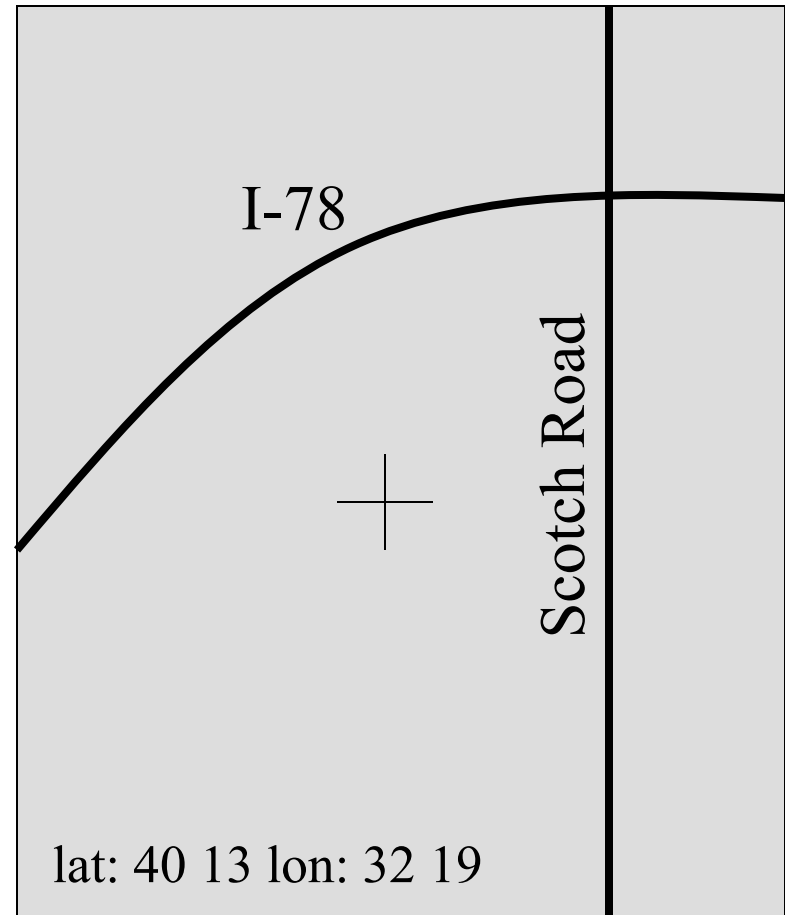
manufacturing cost

power

physical size/weight

# Example: GPS moving map requirements

- Moving map obtains position from GPS, paints map from local database.



# GPS moving map needs

- **Functionality**: For automotive use. Show major roads and landmarks.
- User **interface**: At least 400 x 600 pixel screen. Three buttons max. Pop-up menu.
- **Performance**: Map should scroll smoothly. No more than 1 sec power-up. Lock onto GPS within 15 seconds.
- **Cost**: \$500 street price = approx. \$100

# GPS moving map needs, cont'd.



- **Physical size/weight:** Should fit in dashboard.
- **Power consumption:** Current draw comparable to CD player.



# GPS moving map requirements form



name	GPS moving map
purpose	consumer-grade moving map for driving
inputs	power button, two control buttons
outputs	back-lit LCD 400 X 600
functions	5-receiver GPS; three resolutions; displays current lat/lon
performance	updates screen within 0.25 sec of movement
manufacturing cost	\$100 cost-of-goods-sold
power	100 mW
physical size/weight	no more than 2: X 6:, 12 oz.

# Specification



- A more precise description of the system:
  - should not imply a particular architecture;
  - provides input to the architecture design process.
- May include functional and non-functional elements.
- May be executable or may be in mathematical form for proofs.

# GPS specification



## ■ Should include:

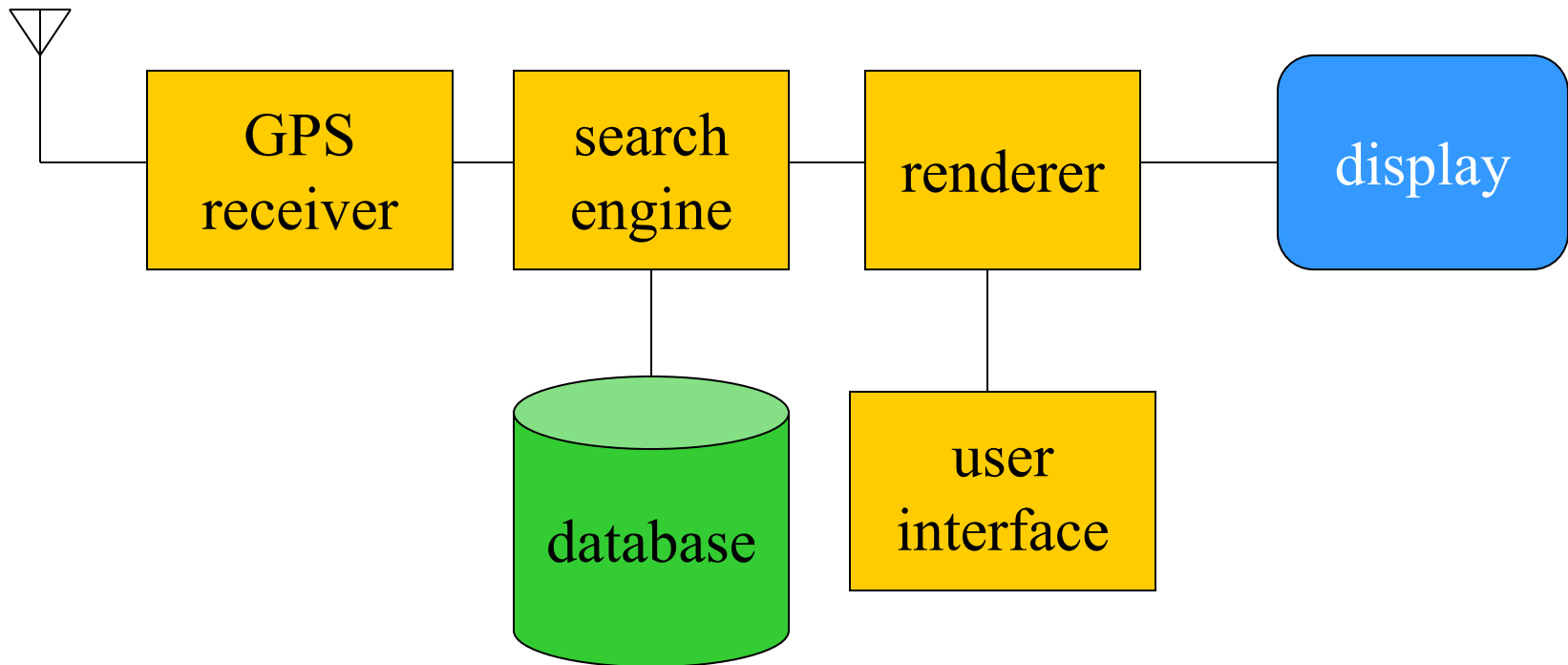
- What is received from GPS;
- map data;
- user interface;
- operations required to satisfy user requests;
- background operations needed to keep the system running.

# Architecture design

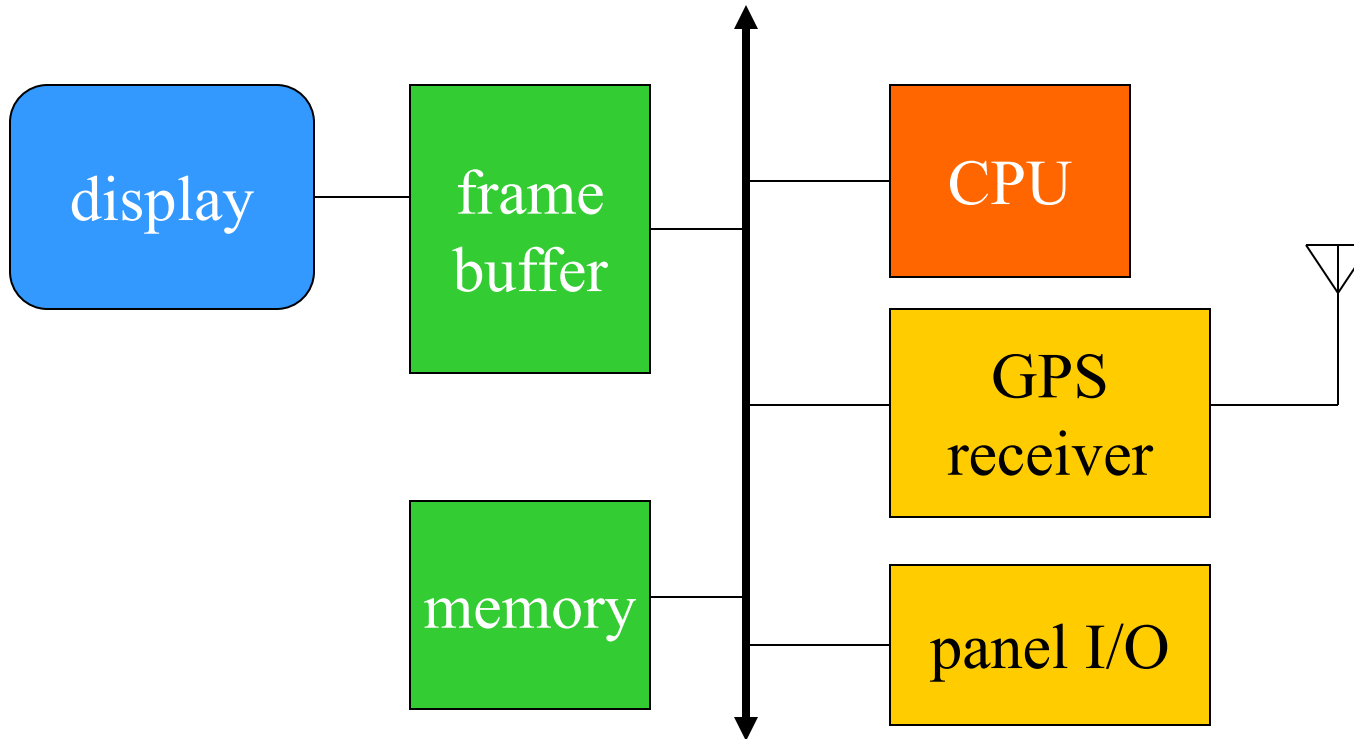


- What major components go satisfying the specification?
- Hardware components:
  - CPUs, peripherals, etc.
- Software components:
  - major programs and their operations.
- Must take into account functional and non-functional specifications.

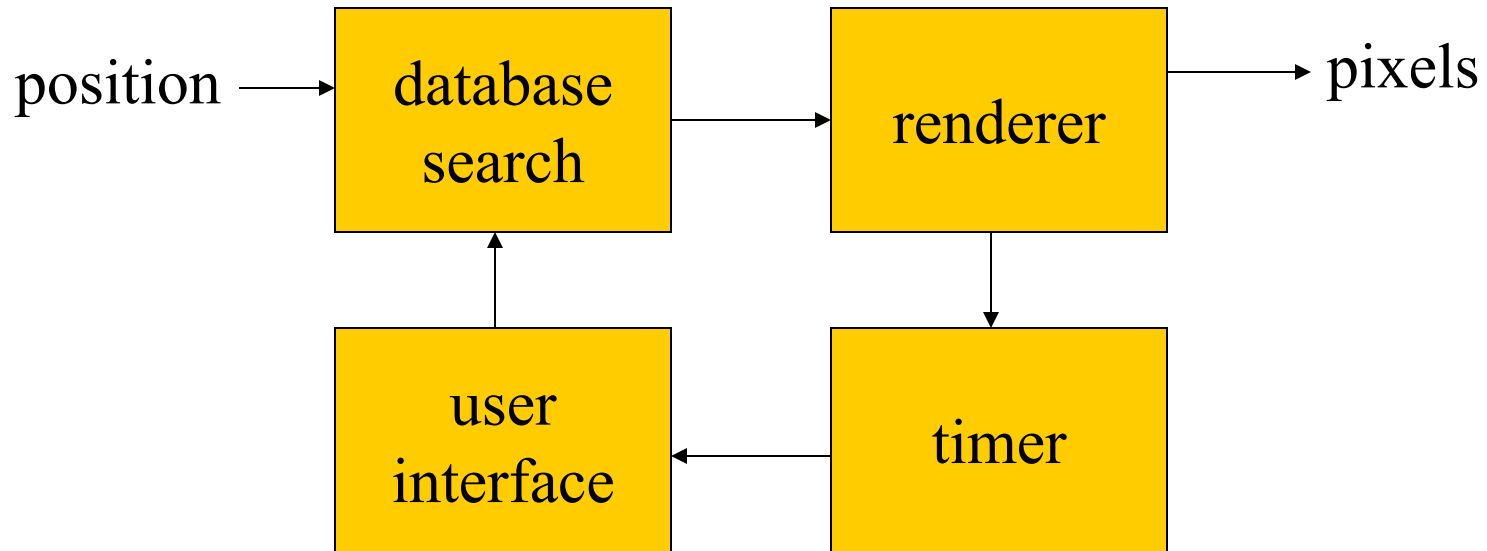
# GPS moving map block diagram



# GPS moving map hardware architecture



# GPS moving map software architecture



# Designing hardware and software components



- Must spend time architecting the system before you start coding.
- Some components are ready-made, some can be modified from existing designs, others must be designed from scratch.



# System integration



- Put together the components.
  - Many bugs appear only at this stage.
- Have a plan for integrating components to uncover bugs quickly, test as much functionality as early as possible.

# Summary



- Embedded computers are all around us.
  - Many systems have complex embedded hardware and software.
- Embedded systems pose many design challenges: design time, deadlines, power, etc.
- Design methodologies help us manage the design process.