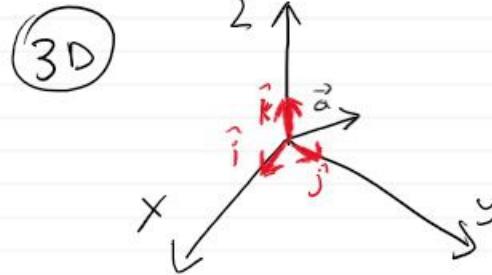
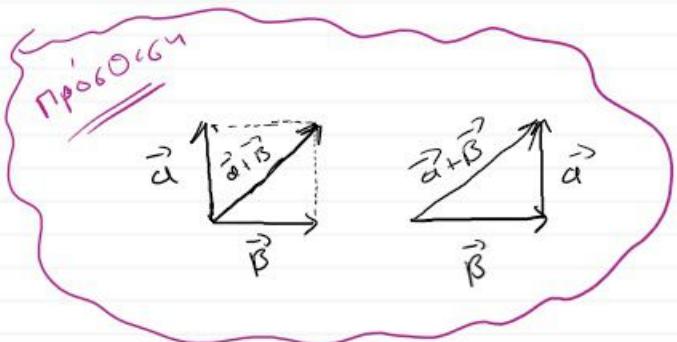
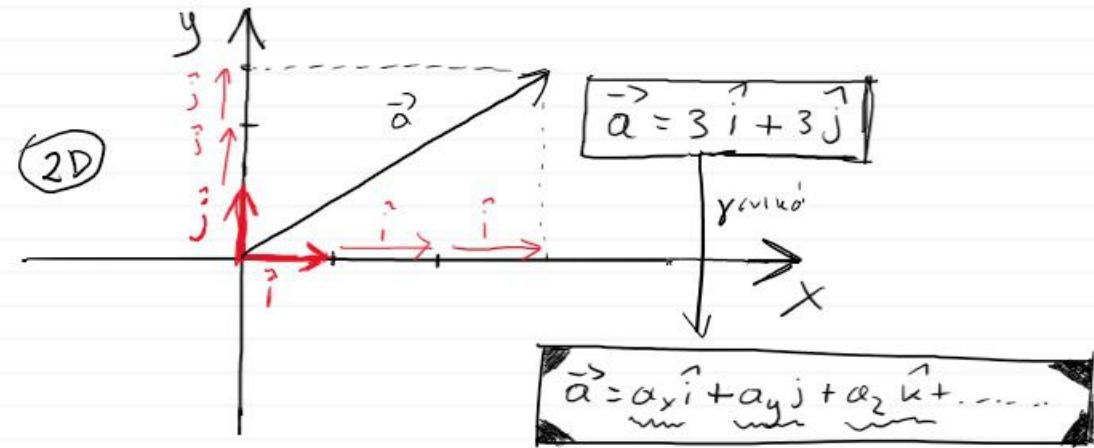
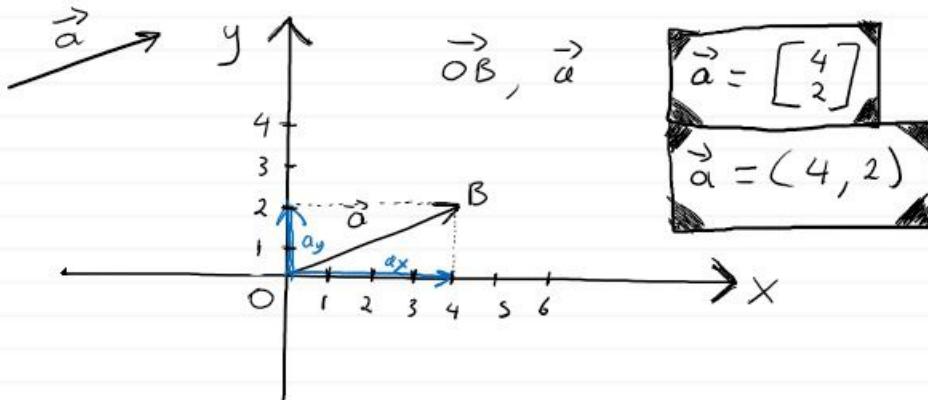




## Diariogpara (Vectors)



## Egavrogy

$$\vec{m} = 4\hat{i} - 2\hat{j} + 3\hat{k}$$

$$\vec{p} = -3\hat{i} + 2\hat{j} + \hat{k}$$

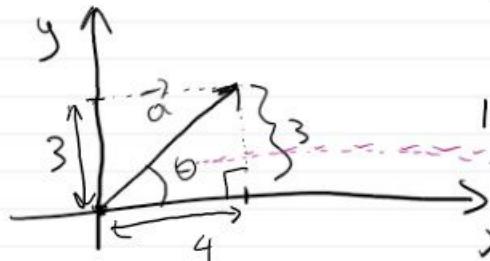
$$\vec{m} + \vec{p} = j$$

$$\vec{m} + \vec{p} = 4\hat{i} + (-3\hat{i}) - 2\hat{j} + 2\hat{j} + 3\hat{k} + \hat{k} = \hat{i} + 4\hat{k}$$





## Mitro Siavugparos



$$\vec{a} = 4\hat{i} + 3\hat{j}$$

$$|\vec{a}| = \sqrt{...}$$

$$|\vec{a}|^2 = 4^2 + 3^2 \Rightarrow |\vec{a}| = \sqrt{4^2 + 3^2} = \sqrt{16 + 9} = \sqrt{25} = 5$$

$$\vec{a} = a_x \hat{i} + a_y \hat{j} + a_z \hat{k} + \dots$$

\* Mitro  $\vec{a} \Rightarrow$

$$|\vec{a}| = \sqrt{a_x^2 + a_y^2 + a_z^2 + \dots}$$

$$\theta = \arctan\left(\frac{3}{4}\right)$$

Epanzopiuus

70°

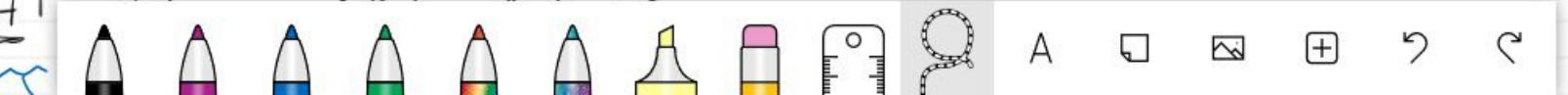
Epanzopiuus: tangent  $\rightarrow$  tan

Auziopiuun: tan $^{-1}$  n arctan n atan

## 'Agumun I

$$\vec{B} = 4\hat{i} - \hat{j}$$

$$|\vec{B}| = \sqrt{4^2 + (-1)^2} = \sqrt{16 + 1} = \sqrt{17} = \sqrt{25} = 5$$



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## Agnan 1

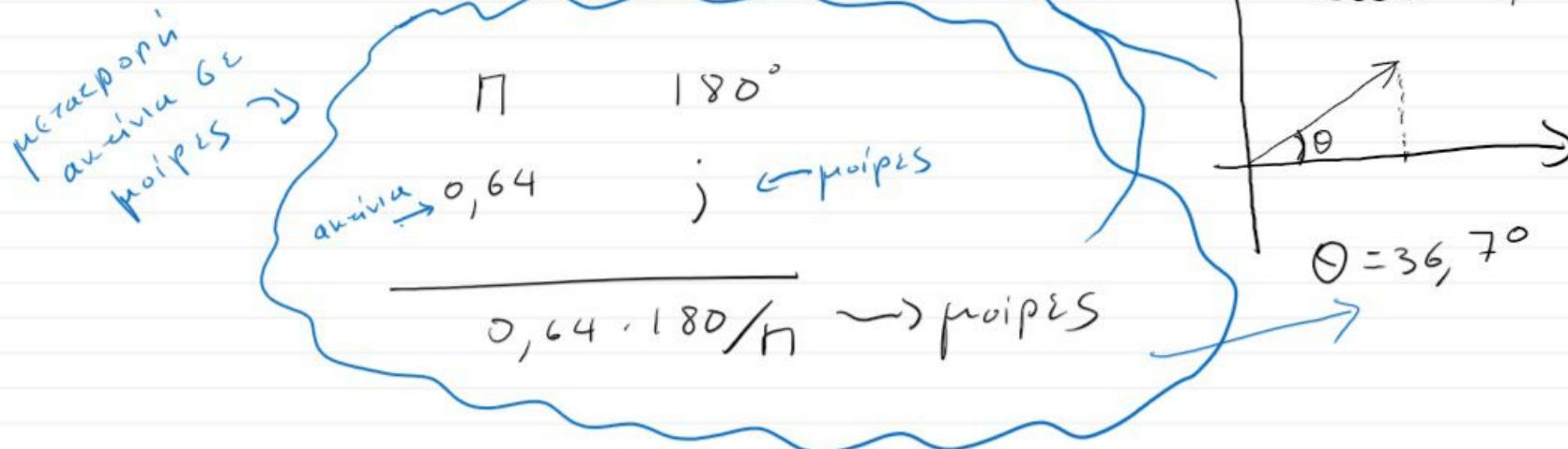
$$\vec{B} = 4\hat{i} + 3\hat{j}$$

$$|\vec{B}| = \sqrt{4^2 + 3^2} = \sqrt{25} = 5$$

$$\Theta = 36,7^\circ$$

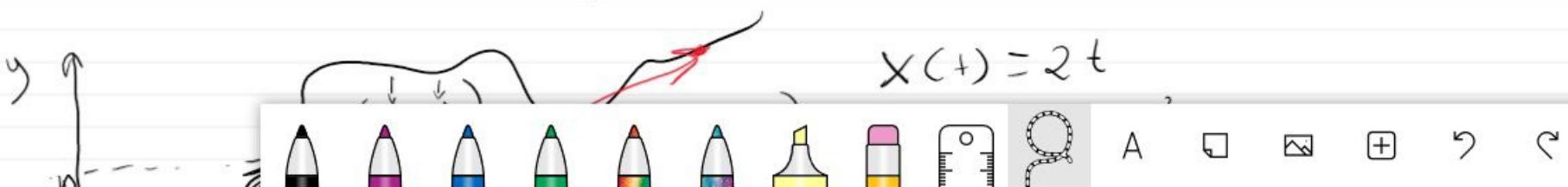
Ep.  $\rightarrow$  tan

$$\tan \Theta = \frac{3}{4}$$



## Agnan 2 $\rightarrow$ [Güpta GE Kivinan]

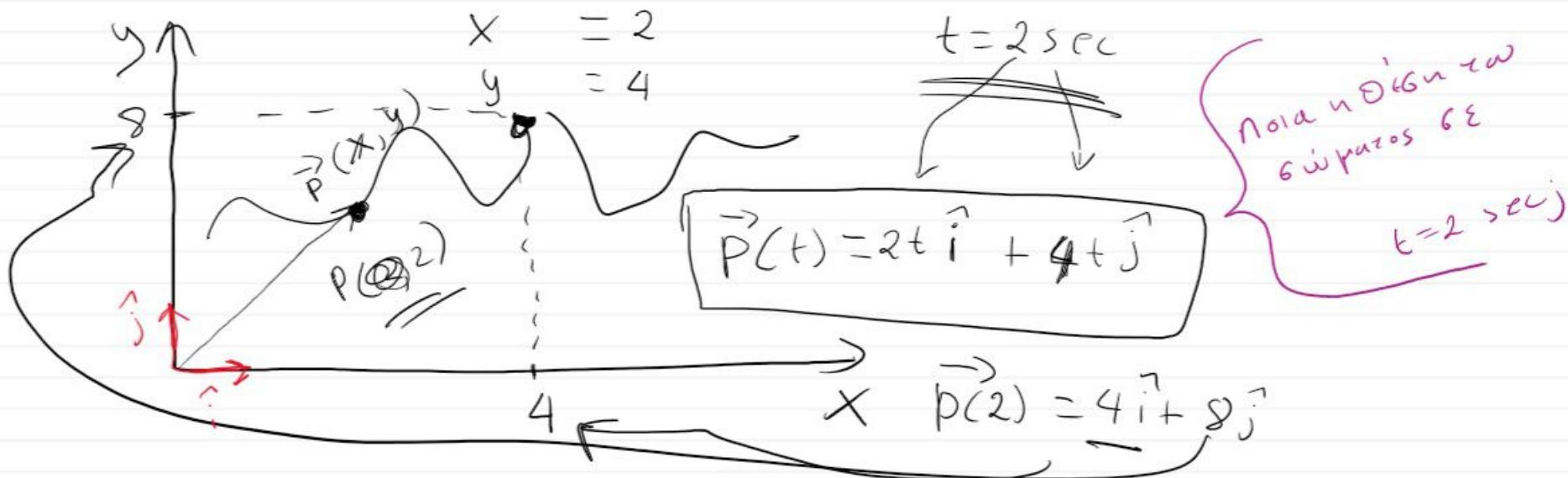
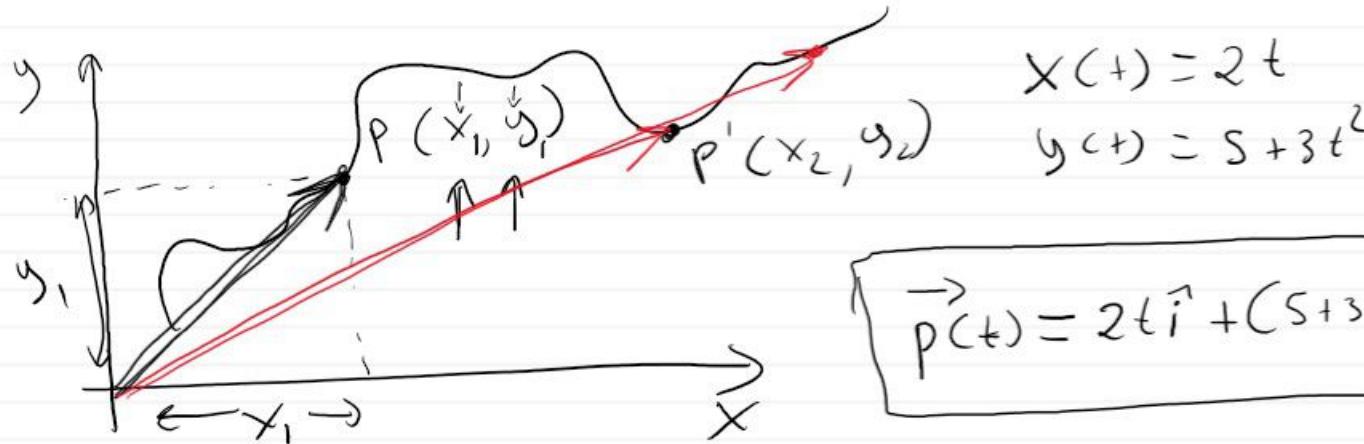
$$t = 1 \text{ sec} / 5 \text{ sec}$$





Aσκηση 2 → [Γύρη σε κίνηση]

$t = 1 \text{ sec} / 5 \text{ sec}$



### 'A' Guna 3

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$$\vec{r}(t) = 2t^2 \hat{i} + (2+3t) \hat{j}$$

$$|\vec{U}| = \sqrt{2^2 + 3^2} \quad t = 2 \text{ sec}$$

$$\vec{v} = \frac{d\vec{r}(t)}{dt}$$

$$\vec{U} = \frac{d\vec{x}}{dt}$$

$$\boxed{\vec{U}(t) = 4t \hat{i} + 3 \hat{j}}$$

$$t=2 \quad \vec{U}(2) = 8 \hat{i} + 3 \hat{j} \quad |\vec{U}(2)| = \sqrt{8^2 + 3^2} = \sqrt{73} \text{ m/s}$$

$$\vec{a} = \frac{d\vec{U}(t)}{dt} \quad \text{in} \quad \frac{d^2 \vec{r}(t)}{dt^2}$$

$$\vec{a} = 4 \hat{i}$$

$$|\vec{a}| = \sqrt{4^2} = 4 \text{ m/s}^2$$

$$\vec{a}(t) = 4t \hat{i}$$

$$\boxed{\vec{F}(t) = 4t \hat{i} - 5t \hat{j}}$$

$$\vec{U}(t) = 4 \hat{i} - 5 \hat{j}$$

$$\vec{O}(t) = \vec{0}$$